

Vrije Universiteit, Faculteit Exacte Wetenschappen,  
Afdeling Informatica

**Herkansing Tentamen Pervasive Computing  
8 Februari 2010**

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Dit is een gesloten boek tentamen.

Tijdens het tentamen mogen geen schriftelijke of elektronische artikelen worden geraadpleegd.

De antwoorden kunnen in het Nederlands of Engels gegeven worden.

Er zijn 5 tentamenvragen, Q1..Q5 en de som ervan is maximaal 90p.

Het tentamencijfer wordt berekend als:  $(Q1+Q2+\dots+Q5+10)/100$

**Het eindcijfer wordt berekend als 0.4\*practicum + 0.6\*tentamen.**

Beide onderdelen moeten  $\geq 5.5$  zijn voor een voldoende.

	Q1	Q2	Q3	Q4	Q5	$\Sigma Q_i$	Maximum = $(\Sigma Q_i + 10) / 10$
a)	5	5	5	10	10		
b)	10	10	10	5	5		
c)			5		5		
d)			5				
e)							
<b>Totaal</b>	<b>15</b>	<b>15</b>	<b>25</b>	<b>15</b>	<b>20</b>	<b>90</b>	<b>10</b>

SUCCES!

### **Q1.Ubiquitous computing vision. DEI model. [15p]**

- ✓ a) [5p] Enumerate the 5 core Ubicom system properties according to the DEI model..
- ✓ b) [10p] Describe an ubicom system with at least 2 of the properties from a) that can enhance the public transport scenario.

### **Q2. Smart devices and services [15p]**

- a) [5p] Enumerate the primary tasks of a smart card operating system
- b) [10p]. There are different service architecture models possible depending on how the A (access), P (processing), C (communication) and I (information) components are distributed. Describe shortly 2 possible models, show in both cases how are the A,P,C and I components distributed and give for both a real life example.

### **Q3. Tagging & sensing [25p]**

- a) [5p] Compare passive and active RFID.
- b) [10p] What is a smart sensor? Draw a diagram and explain the role of each component.
- ✓ c) [5p] Explain how does Time of Arrival (ToA) method work.
- ✓ d) [5p] What is a hard real-time system? Give an example.

### **Q4. Intelligent systems [15p]**

- ✓ a) [10p] Draw a diagram of a reactive intelligent system (R-IS) and explain how it works.
- ✓ b) [5p] Give an example of a R-IS.

### **Q5. Communication.[20p]**

- ✓ a) [10p] What is a parity bit? Show how this works for example for uneven parity when the string "Test" is typed on the keyboard. ASCII table is provided.
- ✓ b) [5p] What is data rate? Calculate the data rate of a 2MHz square wave signal.
- ✓ c) [5p] What is a body area network? Give an example and draw a diagram.

2,5  
2,5 5,5  
5 5,0  
5 4,5  
1 0 1,0  
5 3,0  
5 2,5  
5 2,0  
5 1,5  
1 0

Dec	Hx	Oct	Char	Dec	Hx	Oct	Html	Chr	Dec	Hx	Oct	Html	Chr	Dec	Hx	Oct	Html	Chr
0	000	000	NUL (null)	32	20	040	&#32;	Space	64	40	100	&#64;	Ø	96	60	140	&#96;	'
1	001	S0H	(start of heading)	33	21	041	&#33;	!	65	41	101	&#65;	A	97	61	141	&#97;	a
2	002	STX	(start of text)	34	22	042	&#34;	"	66	42	102	&#66;	B	98	62	142	&#98;	b
3	003	ETX	(end of text)	35	23	043	&#35;	*	67	43	103	&#67;	C	99	63	143	&#99;	c
4	004	EOT	(end of transmission)	36	24	044	&#36;	\$	68	44	104	&#68;	D	100	64	144	&#100;	d
5	005	EJQ	(enquiry)	37	25	045	&#37;	%	69	45	105	&#69;	E	101	65	145	&#101;	e
6	006	ACK	(acknowledge)	00	26	046	&#38;	*	70	46	106	&#70;	F	102	66	146	&#102;	f
7	007	BEL	(bell)	39	27	047	&#39;	'	71	47	107	&#71;	G	103	67	147	&#103;	g
8	010	BS	(backspace)	40	28	050	&#40;	(	72	48	110	&#72;	H	104	68	150	&#104;	h
9	011	TAB	(horizontal tab)	41	29	051	&#41;	)	73	49	111	&#73;	I	105	69	151	&#105;	i
A	012	LF	(NL line feed, new line)	42	2A	052	&#42;	*	74	4A	112	&#74;	J	106	6A	152	&#106;	j
B	013	VT	(vertical tab)	43	2B	053	&#43;	+	75	4B	113	&#75;	K	107	6B	153	&#107;	k
C	014	FF	(NP form feed, new page)	44	2C	054	&#44;	,	76	4C	114	&#76;	L	108	6C	154	&#108;	l
D	015	CR	(carriage return)	45	2D	055	&#45;	-	77	4D	115	&#77;	M	109	6D	155	&#109;	m
E	016	SO	(shift out)	46	2E	056	&#46;	:	78	4E	116	&#78;	N	110	6E	156	&#110;	n
F	017	SI	(shift in)	47	2F	057	&#47;	/	79	4F	117	&#79;	O	111	6F	157	&#111;	o
10	U20	DLE	(data link escape)	48	30	060	&#48;	Ø	80	50	120	&#80;	P	112	70	160	&#112;	p
11	021	DCL	(device control 1)	49	31	061	&#49;	1	81	51	121	&#81;	Q	113	71	161	&#113;	q
12	022	DC2	(device control 2)	50	32	062	&#50;	2	82	52	122	&#82;	R	114	72	162	&#114;	r
13	023	DC3	(device control 3)	51	33	063	&#51;	3	83	53	123	&#83;	S	115	73	163	&#115;	s
14	024	DC4	(device control 4)	52	34	064	&#52;	4	84	54	124	&#84;	T	116	74	164	&#116;	t
15	025	N&K	(negative acknowledge)	53	35	065	&#53;	5	85	55	125	&#85;	U	117	75	165	&#117;	u
16	026	SYN	(synchronous idle)	54	36	066	&#54;	6	86	56	126	&#86;	V	118	76	166	&#118;	v
17	027	ETB	(end of trans. block)	55	37	067	&#55;	7	87	57	127	&#87;	W	119	77	167	&#119;	w
18	030	CAN	(cancel)	56	38	070	&#56;	8	88	58	130	&#88;	X	120	78	170	&#120;	x
19	031	EM	(end of medium)	57	39	071	&#57;	9	89	59	131	&#89;	Y	121	79	171	&#121;	y
1A	032	SUB	(substitute)	58	3A	072	&#58;	:	90	5A	132	&#90;	Z	122	7A	172	&#122;	z
1B	033	ESC	(escape)	59	3B	073	&#59;	:	91	5B	133	&#91;	[	123	7B	173	&#123;	{
1C	034	FS	(file separator)	60	3C	074	&#60;	<	92	5C	134	&#92;	\	124	7C	174	&#124;	
1D	U35	GS	(group separator)	61	3D	075	&#61;	=	93	5D	135	&#93;	]	125	7D	175	&#125;	}
1E	036	RS	(record separator)	62	3E	076	&#62;	>	94	5E	136	&#94;	^	126	7E	176	&#126;	~
1F	037	US	(unit separator)	63	3F	077	&#63;	?	95	5F	137	&#95;	_	127	7F	177	&#127;	DJ

Source: [www.pubbilnet.co](http://www.pubbilnet.co)

ASCII table

128 64 32 16 / 8 4 2 1  
 T = 0 1 1 0 0 1 0 0  
 G 1 1 0 0 1 0 1  
 G 1 1 0 1 1 1  
 G 1 1 0 1 0 1