Department of Computer Science

Exam Computer

Vrije Universiteit

21 - 06 - 2004



This is a "closed book" exam.

No printed materials or electronic devices are admitted for use during the exam. You are supposed to answer the questions in English.

Wishing you lots of success with the exam!

Poin	Points per question (Normering)																
Q	1		2			3		4		5		6	7			8	
	a	b	a	b	c	a	b	a	b	a	b		a	b	c	a	b
P	3	3	4	4	4	9	10	4	4	3	7	14	3	3	3	6	6
Total	l: 90) (+)	10 b	onu	s) =	100											

1. Color

- a) Explain how different colors are composed in the RGB model! Why can the RGB model create colors that are useful for the human observer?
- b) Explain how the CMY color model differs from RGB! What is the main application area for the CMY model?

2. Input Devices

- a) What are the *measure* and *trigger* of an input device? What are the *measure* and *trigger* of a *mouse*? How can this information be derived from the physical mouse device?
- b) Explain the different input modes: request mode, sample mode, event mode! Give examples for each mode! Which input mode is implemented in OpenGL's callback functions? And what is the advantage of doing so?
- c) Write a callback function in the C language using OpenGL (the GLUT library) that allows a user to select a range in the active window using the mouse! The user selects a range by moving the mouse to one corner of the range, pressing the left mouse button, moving the mouse (while keeping the button pressed) to the opposite corner of the range, and finally releasing the mouse button. The screen coordinates have to be filled into the following struct variable range (see below/next page). (It is not necessary that your callback function visualizes the range while selecting.)

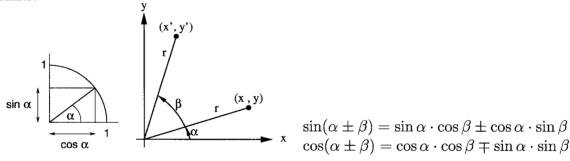
```
typedef struct {
  int x_start, y_start; /* first corner */
  int x_end, y_end; /* opposite corner */
} range_type;
range type range;
```

3. Affine Transformations

In a 2D homogeneous coordinate system, each point P can be represented as $P = P_0 + xv_1 + yv_2$

- a) For this coordinate system, identify the **matrices** for the following transformations:
 - $T(t_x, t_y)$, for a translation by the vector $[t_x, t_y, 0]^T$
 - $S(s_x, s_y)$, for a scaling with the scalars s_x and s_y (and the fix point in the origin)
 - $R(\beta)$, for a *rotation* around the origin by an angle β

Hints:



- b) Let $T_1, T_2, S_1, S_2, R_1, R_2$ be translations, scalings, and rotations, as defined by the matrices from part a). Which of the following transformation pairs are commutative? Show why!
 - i) T_1, T_2
- ii) S_1, S_2
- iii) R_1, R_2
- iv) T_1, S_1
- v) T_1, R_1

4. Hidden Surface Removal

- a) Explain briefly the painter's algorithm! In which cases does the algorithm fail?
- b) Explain *briefly* the z-buffer algorithm! Which issues does the application programmer have to deal with that the algorithm cannot handle by itself?

5. Graphics Objects

- a) Explain the notion and use of "instance transformation" for graphics objects!
- b) Suppose, for an animation program you have a complex graphical object represented by the following, recursive C data structure:

```
typedef struct position {
  /* relative to the parent node in the tree: */
 GLfloat tx,ty,tz; /* translation
                                              */
 GLfloat sx, sy, sz; /* scaling
                                              */
 GLfloat rx,ry,rz; /* rotation axis
                                              * /
                    /* angle of rotation
 GLfloat angle;
                                              */
} position;
typedef struct node {
                              /* key frames 1 and 2
  struct position *p1,*p2;
                                                       */
                              /* setting attributes,
 void (*attrib function)();
                                                        * /
                              /* if not NULL
                                                        */
 void (*drawing function)(); /* drawing the object
                                                       */
  struct node *sibling;
                              /* list of sibling nodes */
  struct node *child;
                              /* list child nodes
                                                       */
} node;
```

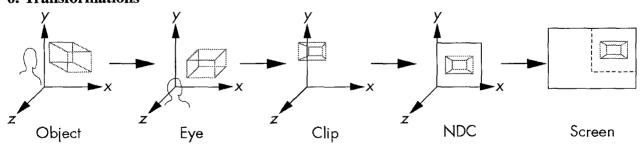
For animating a scene, the graphics object represented with this data structure can be displayed at various intermediate steps between two so-called *key frames*. Assume, you have a C function

that computes in p3 the interpolation between p1 and p2 for a position of percentage. The valid range for percentage is 0..1, where 0 corresponds to p1 and 1 corresponds to p2.

Implement a C function (based on OpenGL):

void display(struct node *tree, GLfloat percentage) that displays the graphical object given in tree! Your function shall produce a single image of the object that corresponds to a frame that lies p% between p1 and p2. (Your function has to traverse all nodes of the tree data structure.) The function attrib_function allows to set atributes like color or material properties; it shall only be called if the pointer is not NULL.

6. Transformations



The image above (previous page) shows the transformations from objects to the screen. Explain the the diagram, focusing on the following terms:

1. clip coordinates

8. object coordinates

2. clipping

9. parallelepiped

3. distortion

10. perspective division

4. eye coordinates

11. projection

5. frustum

12. screen coordinates

6. model-view matrix

13. viewport

7. NDC coordinates

14. view volume

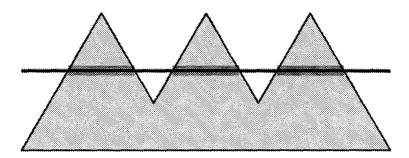
7. Polygon Shading

- a) Explain the basic idea of the *Phong reflection* model! Draw a simple figure that shows the vectors involved in computing the shade of a given point on the surface of an object!
- b) Explain how *flat shading* works, for example for a polygonal mesh! What are the advantage and the disadvantage of flat shading?
- c) Explain *Phong shading* and how it improves over the disadvantage of flat shading!

8. Polygon Filling

a) Show how you can use the XOR operation to implement the odd-even polygon fill algorithm! Assume the simple case in which 0 is the background color and 1 is the edge and fill color. Which writing mode/operation do you use to modify the image?

(Hint: The edges are already drawn before the polygon will be filled.)



b) Implement the flood fill algorithm as a C function

void flood_fill(int x, int y, color_t color); You can read the color of a pixel using color_t read_pixel(int x, int y); and you can write a pixel using void write_pixel(int x, int y, color_t color); Your function flood_fill() can assume that the polygon has been drawn as pixels of color color and that the pixel (x,y) lies inside the polygon.