

Solution mid-term exam Linear Algebra 2022

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$$(a) [A|b] = \left[\begin{array}{cccccc|c} 1 & 0 & 0 & 1 & 1 & 4 & 1 \\ 2 & -1 & 0 & 2 & 1 & 3 & 2 \\ 2 & -1 & 1 & 2 & 1 & 3 & 2 \\ 1 & 0 & 0 & 1 & 1 & 4 & 1 \end{array} \right]$$

$$\sim \left[\begin{array}{cccccc|c} 1 & 0 & 0 & 1 & 1 & 4 & 1 \\ 0 & 1 & 0 & 0 & 1 & 5 & 1 \\ 0 & 0 & 1 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

(b) From the row-reduced echelon form, the pivot columns indicate the vectors that form a basis of $\text{Col}(A)$. Then a basis of $\text{Col}(A)$ is given by

$$B = \{a_1, a_2, a_3\} = \left\{ \begin{bmatrix} 1 \\ 2 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} 0 \\ -1 \\ -1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} \right\}$$

(c) No, since not every column has a pivot.

(d) Since the basis obtained in (b) has 3 vectors, the rank of A is 3.

(e) From the rank theorem, we have

$$\text{rank}(A) + \dim(\text{Nul}(A)) = m,$$

where $m = \#$ of columns. Then

$$3 + \dim(\text{Nul}(A)) = 6$$

$$\therefore \dim(\text{Nul}(A)) = 3.$$

(f) Considering the basis $B = \{a_1, a_2, a_3\}$ and the reduced echelon form we have

$$a_1 = a_1$$

$$a_2 = a_2$$

$$a_3 = a_3$$

$$a_4 = a_1$$

$$a_5 = a_1 + a_2$$

$$a_6 = 4a_1 + 5a_2$$

(g) From the reduced echelon form we can choose x_4, x_5 and x_6 as the 3 free variables. we then have

$$x_1 = -x_4 - x_5 - 4x_6$$

$$x_2 = -x_5 - 5x_6$$

$$x_3 = 0$$

and therefore the general solution has the form

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = \begin{bmatrix} -x_4 - x_5 - 4x_6 \\ -x_5 - 5x_6 \\ 0 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = x_4 \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -1 \\ -1 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} + x_6 \begin{bmatrix} -4 \\ -5 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix},$$

where $x_4, x_5, x_6 \in \mathbb{R}$.

(h) Since the dimension of $\text{Nul}(A) = 3$ we have 3 free variables in the general solution to $Ax = 0$.

(i) From the reduced echelon form we can choose $x_3 = u$, $x_4 = v$, $x_5 = w$ as parameters and write

$$x_1 = 1 - u - v - 4w$$

$$x_2 = 1 - v - 5w$$

$$x_3 = 1$$

$$x_4 = u$$

$$x_5 = v$$

$$x_6 = w$$

then the general solution can be written as

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + u \begin{bmatrix} -1 \\ 0 \\ 0 \\ 1 \\ 0 \\ 0 \end{bmatrix} + v \begin{bmatrix} -1 \\ -1 \\ 0 \\ 0 \\ 1 \\ 0 \end{bmatrix} + w \begin{bmatrix} -4 \\ -5 \\ 0 \\ 0 \\ 0 \\ 1 \end{bmatrix},$$

where $u, v, w \in \mathbb{R}$.

(j) There are many vectors $c \in \mathbb{R}^4$ such that $Ax = c$ has no solution. The only condition needed here is that $c \notin \text{Col}(A)$.

One such vector is

$$c = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}.$$

2] We can write the system in matrix form $Ax = b$, with

$$A = \begin{bmatrix} 1 & 1 & 3 \\ -2 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix} \text{ and } b = \begin{bmatrix} 1 \\ 2 \\ 3 \end{bmatrix}.$$

Note that $\det(A) = -3$ and the system has a unique solution. By Cramer's rule, we have

$$z = \frac{\det(A_3(b))}{\det(A)} = \frac{\det \begin{bmatrix} 1 & 1 & 1 \\ -2 & 2 & 2 \\ 0 & 1 & 3 \end{bmatrix}}{\det(A)}$$

$$= \frac{8}{-3} = -\frac{8}{3}.$$

$$\underline{3} \quad W = \{ x_1 - x_2 + x_3 = 0; x_2 + x_3 - x_4 = 0 \}$$

a) W is a subspace of $\mathbb{R}^4$:

$$(i) \quad 0 = \begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \end{bmatrix} \in W, \text{ since}$$

$$0 - 0 + 0 = 0 \text{ and } 0 + 0 - 0 = 0.$$

$$(ii) \quad \text{Let } u = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{bmatrix} \text{ and } v = \begin{bmatrix} v_1 \\ v_2 \\ v_3 \\ v_4 \end{bmatrix} \in W.$$

$$\text{Then } u+v = \begin{bmatrix} u_1+v_1 \\ u_2+v_2 \\ u_3+v_3 \\ u_4+v_4 \end{bmatrix}. \text{ For } u+v \in W \text{ we need}$$

$$u_1+v_1 - (u_2+v_2) + u_3+v_3 = 0 \text{ and } (u_2+v_2) + (u_3+v_3) - (u_4+v_4) = 0$$

In fact,

$$u_1+v_1 - (u_2+v_2) + u_3+v_3 = u_1 - u_2 + u_3 + v_1 - v_2 + v_3 = 0$$

and

$$(u_2+v_2) + (u_3+v_3) - (u_4+v_4) = u_2 + u_3 - u_4 + v_2 + v_3 - v_4 = 0$$

Therefore $u+v \in W$.

(iii) For $u = \begin{bmatrix} u_1 \\ u_2 \\ u_3 \\ u_4 \end{bmatrix} \in W$ and $c \in \mathbb{R}$,

$$cu = \begin{bmatrix} cu_1 \\ cu_2 \\ cu_3 \\ cu_4 \end{bmatrix} \quad \text{and}$$

$$cu_1 - cu_2 + cu_3 = c(u_1 - u_2 + u_3) = 0,$$

$$cu_2 + cu_3 - cu_4 = c(u_2 + u_3 - u_4) = 0.$$

Therefore $cu \in W$.

From (i), (ii) and (iii) we conclude that W is a subspace of $\mathbb{R}^4$.

(b) We can think of W as the solution set of

$$\begin{aligned} x_1 - x_2 + x_3 &= 0 \\ x_2 + x_3 - x_4 &= 0 \end{aligned} \Rightarrow \begin{aligned} x_1 &= x_2 - x_3 \\ x_4 &= x_2 + x_3 \end{aligned}$$

then, if $x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} \in W$ we have

$$x = \begin{bmatrix} x_2 - x_3 \\ x_2 \\ x_3 \\ x_2 + x_3 \end{bmatrix} = x_2 \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \\ 1 \end{bmatrix}, x_2, x_3 \in \mathbb{R}.$$

$$\text{then } W = \text{span} \left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \\ 1 \end{bmatrix} \right\}$$

the set $\left\{ \begin{bmatrix} 1 \\ \vdots \\ 0 \\ \vdots \end{bmatrix}, \begin{bmatrix} -1 \\ \vdots \\ 0 \\ \vdots \end{bmatrix} \right\}$ is linearly

independent (vectors not multiple of each other).

Therefore a basis of W is

$$B = \left\{ \begin{bmatrix} 1 \\ \vdots \\ 0 \\ \vdots \end{bmatrix}, \begin{bmatrix} -1 \\ \vdots \\ 0 \\ \vdots \end{bmatrix} \right\}$$

(c) From (b) we have that

$$\dim(W) = 2.$$

4 $T: \mathbb{R}^4 \rightarrow \mathbb{P}_2$

$$X = \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \rightarrow T(X) = (a+b)t^2 + bt + c - d$$

(a) Let $x_1 = \begin{bmatrix} a_1 \\ b_1 \\ c_1 \\ d_1 \end{bmatrix}$ and $x_2 = \begin{bmatrix} a_2 \\ b_2 \\ c_2 \\ d_2 \end{bmatrix} \in \mathbb{R}^4$

and $\alpha \in \mathbb{R}$. Then

$$\begin{aligned} \text{(i)} \quad T(x_1 + x_2) &= (a_1 + a_2 + b_1 + b_2)t^2 + (b_1 + b_2)t + c_1 + c_2 - (d_1 + d_2) \\ &= (a_1 + b_1)t^2 + b_1t + c_1 - d_1 + (a_2 + b_2)t^2 + b_2t + c_2 - d_2 \\ &= T(x_1) + T(x_2) \end{aligned}$$

$$\begin{aligned} \text{(ii)} \quad T(\alpha x_1) &= (\alpha a_1 + \alpha b_1)t^2 + \alpha b_1t + \alpha c_1 - \alpha d_1 \\ &= \alpha [(a_1 + b_1)t^2 + b_1t + c_1 - d_1] \\ &= \alpha T(x_1) \end{aligned}$$

From (i) and (ii) T is linear.

$$(b) \text{Ker}(T) = \{x \in \mathbb{R}^4 : T(x) = 0\}$$

For $x = \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \in \text{Ker}(T)$ we need

$$T(x) = 0, \text{ that is}$$

$$(a+b)t^2 + bt + c - d = 0 \in \mathbb{R}_2.$$

Then

$$\begin{array}{lcl} a+b=0 & & a=b=0 \\ b=0 & \Rightarrow & c=d \\ c-d=0 & & \end{array}$$

Therefore, if $x \in \text{Ker}(T)$, we have

$$x = \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ c \\ c \end{bmatrix} = c \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix}, \quad c \in \mathbb{R}.$$

and then

$$\text{Ker}(T) = \text{span} \left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \\ 1 \end{bmatrix} \right\}$$

$$(c) \text{ Range}(T) = \{ p \in \mathbb{P}_2 : T(x) = p \text{ for } x \in \mathbb{R}^4 \}$$

Let $p(t) = At^2 + Bt + C \in \mathbb{P}_2$. If $p \in \text{Range}(T)$ there must exist $x = \begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} \in \mathbb{R}^4$ such that

$$T(x) = p. \text{ That is}$$

$$(a+b)t^2 + bt + c-d = At^2 + Bt + C.$$

We then have the system

$$a+b = A$$

$$b = B$$

$$c-d = C$$

or

$$\left[\begin{array}{cccc|c} 1 & 1 & 0 & 0 & A \\ 0 & 1 & 0 & 0 & B \\ 0 & 0 & 1 & -1 & C \end{array} \right].$$

This system is always consistent, since there are pivots in each column. Therefore any $p \in \mathbb{P}_2$ is the image of some $x \in \mathbb{R}^4$ under T . From here,

$$\text{Range}(T) = \mathbb{P}_2.$$

5]

(a) True.

If AB is invertible, then

$$\det(AB) \neq 0$$

$$\Rightarrow \det(A) \cdot \det(B) \neq 0$$

$$\Rightarrow \det(A) \neq 0 \text{ and } \det(B) \neq 0.$$

Therefore A and B are both invertible.

(b) True.

Let $c_1, \dots, c_n$ be scalars such that

$$c_1 v_1 + c_2 v_2 + \dots + c_n v_n = 0 \in V.$$

then

$$T(c_1 v_1 + \dots + c_n v_n) = T(0) = 0 \in U$$

T linear

$$\Rightarrow c_1 T(v_1) + \dots + c_n T(v_n) = 0 \in U$$

since $T(v_1), \dots, T(v_n)$ are l.i., we must have

$$c_1 = c_2 = \dots = c_n = 0$$

so $v_1, \dots, v_n$ are l.i.

(c) True.

Since B and C are bases of V , there exists a unique change of coordinates matrix from B to C , ${}^C_P B$, whose columns are the coordinates of the vectors of B relative to C .

P is $n \times n$ and also invertible.
 $C \leftarrow B$

From the IMT, the rank of ${}^C_P B$ has to be n .