

linear Algebra

Exam 2 , 2021

Solutions

$$1a. \begin{vmatrix} 3-\lambda & -4 \\ 5 & -1-\lambda \end{vmatrix} = (3-\lambda)(-1-\lambda) + 20$$

$$\lambda^2 - 2\lambda + 17 = 0$$

$$(\lambda-1)^2 = -16$$

$$\lambda_1 = 1+4i, \quad \lambda_2 = 1-4i$$

$$1b. A - (1+4i)I = \begin{bmatrix} 2-4i & -4 \\ 5 & -2-4i \end{bmatrix} \sim \begin{bmatrix} 1-2i & -2 \\ 0 & 0 \end{bmatrix}$$

gives  $\underline{v}_1 = \begin{bmatrix} 2 \\ 1-2i \end{bmatrix}$ .

basis eigenspace  $\lambda_1 = 1+4i : \left\{ \begin{bmatrix} 2 \\ 1-2i \end{bmatrix} \right\}$

basis eigenspace  $\lambda_2 = 1-4i : \left\{ \begin{bmatrix} 2 \\ 1+2i \end{bmatrix} \right\} (= \bar{\underline{v}}_1)$

$$2a. \begin{vmatrix} 1-\lambda & 0 & 0 & 2 \\ 0 & 2-\lambda & 0 & xe \\ 0 & 0 & 1-\lambda & 0 \\ 0 & 0 & 2 & 2-\lambda \end{vmatrix} = (1-\lambda) \begin{vmatrix} 1-\lambda & 0 & 2 \\ 0 & 2-\lambda & xe \\ 0 & 0 & 2-\lambda \end{vmatrix}$$

$$= (1-\lambda)(1-\lambda)(2-\lambda)(2-\lambda) = 0$$

$$\lambda_1 = 1, \quad \lambda_2 = 2$$

(both multiplicity 2)

$$2b. B - 2I = \begin{bmatrix} -1 & 0 & 0 & 2 \\ 0 & 0 & 0 & xe \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 2 & 0 \end{bmatrix}$$

There must be two free variables. This is only the case for  $xe = 0$ .

$$2c. \text{ Consider } B - I = \begin{bmatrix} 0 & 0 & 0 & 2 \\ 0 & 1 & 0 & xe \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 1 \end{bmatrix}$$

There must be two free variables. But for any value of  $xe$ , there is only one free variable. So,  $B$  is not diagonalizable for any value of  $xe$ .

3a. Note that the columns of  $C$  are orthogonal.  
Therefore, we can use the formula

$$\begin{aligned}\hat{\underline{y}}_d &= \frac{\underline{y} \cdot \underline{c}_1}{\underline{c}_1 \cdot \underline{c}_1} \underline{c}_1 + \frac{\underline{y} \cdot \underline{c}_2}{\underline{c}_2 \cdot \underline{c}_2} \underline{c}_2 + \frac{\underline{y} \cdot \underline{c}_3}{\underline{c}_3 \cdot \underline{c}_3} \underline{c}_3 \\ &= \frac{10}{10} \underline{c}_1 + \frac{30}{10} \underline{c}_2 + 0 \underline{c}_3 = \begin{bmatrix} 2 \\ -1 \\ 2 \\ -1 \end{bmatrix} + \begin{bmatrix} 3 \\ 6 \\ 3 \\ 6 \end{bmatrix} = \begin{bmatrix} 5 \\ 5 \\ 5 \\ 5 \end{bmatrix}\end{aligned}$$

3b. From part (a) we know  $\hat{\underline{y}}_d = 1 \cdot \underline{c}_1 + 3 \cdot \underline{c}_2 + 0 \cdot \underline{c}_3$ ,  
so the least-squares solution is  $\hat{\underline{x}} = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}$ .

Or solve the normal equations  $C^T C \hat{\underline{x}} = C^T \underline{y}$ :

$$C^T C = \begin{bmatrix} 10 & 0 & 0 \\ 0 & 10 & 0 \\ 0 & 0 & 2 \end{bmatrix}, \quad C^T \underline{y} = \begin{bmatrix} 10 \\ 30 \\ 0 \end{bmatrix} \Rightarrow \hat{\underline{x}} = \begin{bmatrix} 1 \\ 3 \\ 0 \end{bmatrix}.$$

3c.  $\|\underline{y} - \hat{\underline{y}}_d\| = \left\| \begin{bmatrix} 5 \\ 0 \\ 5 \\ 10 \end{bmatrix} - \begin{bmatrix} 5 \\ 5 \\ 5 \\ 5 \end{bmatrix} \right\| = \left\| \begin{bmatrix} 0 \\ -5 \\ 0 \\ 5 \end{bmatrix} \right\| = \sqrt{5^2 + 5^2} = \sqrt{50} (= 5\sqrt{2})$

$\uparrow$   
 $(= \|\underline{y} - C \hat{\underline{x}}\|)$

$$4a. MM^T = \begin{bmatrix} 1 & 0 & -1 & 0 \\ 1 & 1 & 1 & -1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ -1 & 1 \\ 0 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 4 \end{bmatrix}. \quad \lambda_1 = 2, \quad \lambda_2 = 4.$$

4b. Let  $\lambda \neq 0$  be an eigenvalue of  $AA^T$ , then

$$AA^T \underline{x} = \lambda \underline{x} \text{ for some nonzero } \underline{x}.$$

It follows that  $A^T(AA^T\underline{x}) = A^T(\lambda \underline{x})$ , so

$$A^TA(A^T\underline{x}) = \lambda(A^T\underline{x}), \text{ with } A^T\underline{x} \text{ nonzero.}$$

Hence  $\lambda$  is an eigenvalue of  $A^TA$ .

4c. This means that the eigenvalues of  $M^TM$  are  $\lambda_1 = 2, \lambda_2 = 4$  and (possibly)  $\lambda_3 = 0$ .

$$4d. M^TM = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ -1 & 1 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} 1 & 0 & -1 & 0 \\ 1 & 1 & 1 & -1 \\ 1 & 1 & 1 & -1 \\ 0 & 1 & 2 & -1 \end{bmatrix} = \begin{bmatrix} 2 & 1 & 0 & -1 \\ 1 & 1 & 1 & -1 \\ 0 & 1 & 2 & -1 \\ -1 & -1 & -1 & 1 \end{bmatrix}$$

$$M^TM - 2I = \begin{bmatrix} 0 & 1 & 0 & -1 \\ 1 & -1 & 1 & -1 \\ 0 & 1 & 0 & -1 \\ -1 & -1 & -1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \underline{v}_1 = \begin{bmatrix} 1 \\ 0 \\ -1 \\ 0 \end{bmatrix}$$

Orthogonal basis eigenspace  $\lambda_1 = 2 : \left\{ \begin{bmatrix} 1 \\ 0 \\ -1 \\ 0 \end{bmatrix} \right\}$

$$M^T M - 4I = \begin{bmatrix} -2 & 1 & 0 & -1 \\ 1 & -3 & 1 & -1 \\ 0 & 1 & -2 & -1 \\ -1 & -1 & -1 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \underline{v}_2 = \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix}$$

Orthogonal basis eigenspace  $\lambda_2 = 4 : \left\{ \begin{bmatrix} 1 \\ 1 \\ -1 \\ -1 \end{bmatrix} \right\}$

$$M^T M = \begin{bmatrix} 2 & 1 & 0 & -1 \\ 1 & 1 & 1 & -1 \\ 0 & 1 & 2 & -1 \\ -1 & -1 & -1 & 1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & -1 & 0 \\ 0 & 1 & 2 & -1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} \rightarrow \underline{v}_3 = \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \underline{v}_4 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix}$$

Note that  $\underline{v}_3$  and  $\underline{v}_4$  are not orthogonal.

$$\text{Compute } \underline{x}_4 = \underline{v}_4 - \frac{\underline{v}_4 \cdot \underline{v}_3}{\underline{v}_3 \cdot \underline{v}_3} \underline{v}_3 = \underline{v}_4 - \frac{-2}{6} \underline{v}_3 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ 1 \end{bmatrix} + \begin{bmatrix} 1/3 \\ -2/3 \\ 1/3 \\ 0 \end{bmatrix} = \begin{bmatrix} 1/3 \\ 1/3 \\ 1/3 \\ 1 \end{bmatrix}.$$

Orthogonal basis eigenspace  $\lambda_3 = 0 : \left\{ \begin{bmatrix} 1 \\ -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ 1 \\ 3 \end{bmatrix} \right\}$

4e. Normalize the eigenvectors:

$$\underline{u}_1 = \begin{bmatrix} 1/\sqrt{2} \\ 0 \\ -1/\sqrt{2} \\ 0 \end{bmatrix}, \quad \underline{u}_2 = \begin{bmatrix} 1/2 \\ 1/2 \\ 1/2 \\ -1/2 \end{bmatrix}, \quad \underline{u}_3 = \begin{bmatrix} 1/\sqrt{6} \\ -2/\sqrt{6} \\ 1/\sqrt{6} \\ 0 \end{bmatrix}, \quad \underline{u}_4 = \begin{bmatrix} 1/\sqrt{12} \\ 1/\sqrt{12} \\ 1/\sqrt{12} \\ 3/\sqrt{12} \end{bmatrix}$$

$$M^T M = P D P^T \text{ with}$$

$$P = \begin{bmatrix} 1/\sqrt{2} & 1/2 & 1/\sqrt{6} & 1/\sqrt{12} \\ 0 & 1/2 & -2/\sqrt{6} & 1/\sqrt{12} \\ -1/\sqrt{2} & 1/2 & 1/\sqrt{6} & 1/\sqrt{12} \\ 0 & -1/2 & 0 & 3/\sqrt{12} \end{bmatrix} \text{ and } D = \begin{bmatrix} 2 & 0 & 0 & 0 \\ 0 & 4 & 0 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

5a. True If  $A$  has a zero column, then  $A$  is not invertible, and by the Invertible Matrix Theorem,  $\lambda=0$  is an eigenvalue of  $A$ .

5b. False  $\langle \underline{u}, \underline{u} \rangle = u_1 u_1 + u_2 u_2 = 2u_1 u_2 \neq 0$   
for some  $\underline{u} \in \mathbb{R}^2$ .

(Counterexample:

$$\underline{u} = \begin{bmatrix} 1 \\ -2 \end{bmatrix}, \text{ then } \langle \underline{u}, \underline{u} \rangle = -4.$$

5c. True  $\text{Col } A$  is a subspace of  $\mathbb{R}^n$ .

By the Orthogonal Decomposition Theorem, each  $\underline{y}$  in  $\mathbb{R}^n$  can be written (uniquely) in the form  $\underline{y} = \hat{\underline{y}} + \underline{z}$ , with  $\hat{\underline{y}} \in \text{Col } A$  and  $\underline{z} \in (\text{Col } A)^\perp$ .

Note that  $(\text{Col } A)^\perp = \text{Nul } A^\top = \text{Nul } A$ , since  $A$  is symmetric.

5d. True If  $A$  is orthogonally diagonalizable, then  $A$  is symmetric. So,  $A^T = A$ . Consider  $(A^2)^T = (A \cdot A)^T = A^T \cdot A^T = (A^T)^2 = A^2$ . So,  $A^2$  is symmetric, which implies that  $A^2$  is orthogonally diagonalizable.

6. Use Gram-Schmidt:

$$v_1(t) = p(t) = 1$$

$$v_2(t) = q(t) - \frac{\langle q, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1$$

$$\langle q, v_1 \rangle = 2 \cdot 1 + 4 \cdot 1 + 6 \cdot 1 + 8 \cdot 1 = 20$$

$$\langle v_1, v_1 \rangle = 1 \cdot 1 + 1 \cdot 1 + 1 \cdot 1 + 1 \cdot 1 = 4$$

$$v_2(t) = 2t - \frac{20}{4} \cdot 1 = 2t - 5$$

$$v_3(t) = r(t) - \frac{\langle r, v_1 \rangle}{\langle v_1, v_1 \rangle} v_1 - \frac{\langle r, v_2 \rangle}{\langle v_2, v_2 \rangle} v_2$$

$$\langle r, v_1 \rangle = -3 \cdot 1 + -4 \cdot 1 + -3 \cdot 1 + 0 \cdot 1 = -10$$

$$\langle r, v_2 \rangle = -3 \cdot -3 + -4 \cdot -1 + -3 \cdot 1 + 0 \cdot 3 = 10$$

$$\langle v_2, v_2 \rangle = -3 \cdot -3 + -1 \cdot -1 + 1 \cdot 1 + 3 \cdot 3 = 20$$

$$v_3(t) = t^2 - 4t - \frac{-10}{4} \cdot 1 - \frac{10}{20} (2t - 5)$$

$$= t^2 - 4t + \frac{5}{2} - t + \frac{5}{2}$$

$$= t^2 - 5t + 5.$$

orthogonal basis:  $\{1, 2t - 5, t^2 - 5t + 5\}$