

1. a. $A \underline{v} = \begin{bmatrix} 3 & -1 & 2 \\ -2 & 2 & -2 \\ 1 & -\frac{1}{2} & 2 \end{bmatrix} \begin{bmatrix} 2 \\ -2 \\ 1 \end{bmatrix} = \begin{bmatrix} 10 \\ -10 \\ 5 \end{bmatrix} = 5 \underline{v}. \quad 2$

b. $\det(A - \lambda I) = -\lambda^3 + 7\lambda^2 - 11\lambda + 5 = \chi(\lambda)$

$\lambda = 5$ is eigenwaarde $\rightarrow \chi(\lambda) = (\lambda - 5)g(\lambda) \quad 1$

(Factoren: $(5 - \lambda)(\lambda - 1)^2$. 1

Eigenruimte bij $\lambda = 1$:

$$A - I = \begin{bmatrix} 2 & -1 & 2 \\ -2 & 1 & -2 \\ 1 & -\frac{1}{2} & 1 \end{bmatrix} \sim \dots \sim \begin{bmatrix} 1 & -\frac{1}{2} & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

De $\text{Eig}_{\lambda=1}$ wordt opgespannen door $\underline{v}_2$

$\underline{v}_2 = \begin{bmatrix} 1 \\ 2 \\ 0 \end{bmatrix}$ en $\underline{v}_3 = \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} \quad 2$

c. $\dim \text{Eig}_{\lambda=1} = 2 = \text{alg. mult. van } \lambda = 1 \text{ in } \chi(\lambda).$

idem voor $\lambda = 5$. Dus A is diag. baar. 2

Ook: $\underline{v}_1, \underline{v}_2$ en $\underline{v}_3$ vormen basis van $\mathbb{R}^3$. Dit

is een alternatief antwoord. $P = [\underline{v}_1 \ \underline{v}_2 \ \underline{v}_3]$. $D = \text{diag}(5, 1, 1)$

d. ~~Nee~~. Nee. A is orth. diag baar $\Leftrightarrow A$ is symmetrisch.
Hier is $A \neq A^T$ dus niet symm. 1

2. a. Last $\underline{w}_1 = \begin{bmatrix} 2 \\ 4 \\ 0 \\ -4 \end{bmatrix}$ $\|\underline{w}_1\|^2 = 36$.

$\underline{w}_2 = \begin{bmatrix} 3 \\ 2 \\ 2 \\ -1 \end{bmatrix} - \frac{\begin{bmatrix} 3 \\ 2 \\ 2 \\ -1 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 4 \\ 0 \\ -4 \end{bmatrix}}{36} \begin{bmatrix} 2 \\ 4 \\ 0 \\ -4 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \\ 2 \\ 1 \end{bmatrix}$ $\|\underline{w}_2\| = 9$

$\underline{w}_3 = \begin{bmatrix} 2 \\ 5 \\ 4 \\ -3 \end{bmatrix} - \frac{\begin{bmatrix} 2 \\ 5 \\ 4 \\ -3 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 4 \\ 0 \\ -4 \end{bmatrix}}{36} \begin{bmatrix} 2 \\ 4 \\ 0 \\ -4 \end{bmatrix} - \frac{\begin{bmatrix} 2 \\ 5 \\ 4 \\ -3 \end{bmatrix} \cdot \begin{bmatrix} 2 \\ 0 \\ 2 \\ 1 \end{bmatrix}}{9} \begin{bmatrix} 2 \\ 0 \\ 2 \\ 1 \end{bmatrix} =$

$\begin{bmatrix} -2 \\ 1 \\ 2 \\ 0 \end{bmatrix}$ $\|\underline{w}_3\| = 9$.

Das ONB ist $\left\{ \frac{\underline{w}_1}{\|\underline{w}_1\|}, \frac{\underline{w}_2}{\|\underline{w}_2\|}, \frac{\underline{w}_3}{\|\underline{w}_3\|} \right\} = \left\{ \begin{bmatrix} +1/3 \\ +2/3 \\ 0 \\ 2/3 \end{bmatrix}, \begin{bmatrix} 2/3 \\ 0 \\ 2/3 \\ 1/3 \end{bmatrix}, \begin{bmatrix} -2/3 \\ 1/3 \\ 2/3 \\ 0 \end{bmatrix} \right\}$.

b. Last $Q = \frac{1}{3} \begin{bmatrix} +1 & 2 & -2 \\ +2 & 0 & 1 \\ 0 & 2 & 2 \\ -2 & 1 & 0 \end{bmatrix}$ $Q^T Q = I_3$.

Da $A = QR$ gilt $Q^T A = Q^T Q R = R$.

Da $R = \frac{1}{3} \begin{bmatrix} +1 & +2 & 0 & -2 \\ 2 & 0 & 2 & 1 \\ -2 & 1 & 2 & 0 \end{bmatrix} \begin{bmatrix} 2 & 3 & 2 \\ 4 & 2 & 5 \\ 0 & 2 & 4 \\ -4 & -1 & -3 \end{bmatrix} = \begin{bmatrix} +6 & +3 & -6 \\ 0 & 3 & 3 \\ 0 & 0 & 3 \end{bmatrix}$

Approximation: on $R_{11} > 0$ te R_{11} nehmen wir
 Zeilen R_{11} von Q $\begin{bmatrix} 1/3 \\ 2/3 \\ 0 \\ 2/3 \end{bmatrix}$ $\begin{bmatrix} 2/3 \\ 0 \\ 2/3 \\ 1/3 \end{bmatrix}$ $\begin{bmatrix} -2/3 \\ 1/3 \\ 2/3 \\ 0 \end{bmatrix}$ $\begin{bmatrix} 2 \\ 0 \\ 2 \\ 1 \end{bmatrix}$

$$c. \quad \underline{b}_1 = \text{proj}_{\text{Col } A} \underline{b} =$$

$$\text{last } Q = [\underline{q}_1, \underline{q}_2, \underline{q}_3].$$

$$(\underline{b} \cdot \underline{q}_1) \underline{q}_1 + (\underline{b} \cdot \underline{q}_2) \underline{q}_2 + (\underline{b} \cdot \underline{q}_3) \underline{q}_3$$

$$= \begin{bmatrix} 0 \\ -1/3 \\ 2/3 \\ 2/3 \end{bmatrix} \quad \underline{b}_2 = \underline{b} - \underline{b}_1 = \begin{bmatrix} 0 \\ 4/3 \\ -2/3 \\ 4/3 \end{bmatrix}$$

$$3. a. \text{ last } A = [\underline{v}_1, \underline{v}_2] = \begin{bmatrix} 1 & 2 \\ -1 & 4 \\ 1 & 2 \end{bmatrix}$$

$$\text{Op } k \text{ losse } A^T A \underline{x} = A^T \underline{y}$$

$$\Leftrightarrow \begin{bmatrix} 3 & 0 \\ 0 & 24 \end{bmatrix} \underline{x} = \begin{bmatrix} 9 \\ 12 \end{bmatrix}$$

$$\text{Dah } \underline{x} = \begin{bmatrix} 3 \\ 1/2 \end{bmatrix}$$

$$b. \quad A \underline{x} = \begin{bmatrix} +4 \\ -1 \\ 4 \end{bmatrix} \quad \underline{y} = \begin{bmatrix} 3 \\ -1 \\ 5 \end{bmatrix} \Rightarrow$$

$$\text{dist}(\underline{y}, V) = \|\underline{y} - \text{proj}_V \underline{y}\|$$

$$= \|\underline{y} - A \underline{x}\| = \left\| \begin{bmatrix} 3 \\ -1 \\ 5 \end{bmatrix} - \begin{bmatrix} 4 \\ -1 \\ 4 \end{bmatrix} \right\|$$

$$= \left\| \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\| = \sqrt{2}$$

4. a. A diagbaar $\Rightarrow \exists P, D: A = P D P^{-1}$

B gelijw. aan $A \Rightarrow \exists C: A = C^{-1} B C$

$$\begin{aligned} \text{Dm } B &= C^{-1} A C \\ &= C^{-1} P D P^{-1} C \\ &= (CP) D (CP)^{-1} \end{aligned}$$

$\circ$ dm B is diag. baar.

5. De bijbehorende matrix is $A = \begin{bmatrix} 3 & -2 \\ -2 & 4 \end{bmatrix}$

(zodat $Q(x) = x^T A x$).

A heeft eigenwaarden gegeven door $\chi(\lambda) = (3-\lambda)(4-\lambda) \stackrel{!}{=} 0$

$$\lambda^2 - 7\lambda + 8 = 0$$

$$\lambda = \frac{7}{2} \pm \frac{1}{2} \sqrt{49 - 32}$$

$$= \frac{7}{2} \pm \frac{1}{2} \sqrt{17}$$

$$4 < \sqrt{17} < 5$$

dm $\frac{7}{2} - \frac{1}{2} \sqrt{17} > 0 \Rightarrow$ beide λ 's strikt pos.

dm pos. definit. 2

(Ook kan: $\det A = 8 > 0, \operatorname{tr} A = 7 > 0 \left. \vphantom{\begin{matrix} \det A = 8 > 0 \\ \operatorname{tr} A = 7 > 0 \end{matrix}} \right\} \lambda_1, \lambda_2 > 0$)

c. Nee. Als $\underline{v}_1, \underline{v}_2 \in \text{Eig}_\lambda$ geldt

$c_1 \underline{v}_1 + c_2 \underline{v}_2 \in \text{Eig}_\lambda$ dan heeft zeker niet

dat $\underline{v}_1 \cdot \underline{v}_2 = 0$. Elk paar lin. onafh. vectoren in Eig_λ spannen de eigenruimte op, en slechts enkele staa loodrecht op elkaar.

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(Evt concreet tegenvb: als $\underline{v}_1, \underline{v}_2$ lin. onafh

en $\underline{v}_1 \cdot \underline{v}_2 = 0$ dan $\underline{v}_1 + \underline{v}_2$ ook lin. onafh

maar $(\underline{v}_1 \cdot (\underline{v}_1 + \underline{v}_2)) = \|\underline{v}_1\|^2 \neq 0$.)

$$d. \|\underline{U}\underline{x}\|^2 = (\underline{U}\underline{x} \cdot \underline{U}\underline{x}) = \underline{x}^T \underline{U}^T \underline{U} \underline{x} = \underline{x}^T \underline{x} = \|\underline{x}\|^2$$

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als $\underline{U}$ een orthogonale matrix

is. Maar $\underline{U}$ heeft slechts onth. kolommen!

Daar geldt $\underline{U}^T \underline{U} = \underline{I}$ zomaar. Dan is het algemeen met van.

(1,5 pt als $\underline{U}^T \underline{U} = \underline{I}$ aangenomen)

$$n. V = C([-1, 1]; \mathbb{R}). \quad \langle \cdot, \cdot \rangle: V \times V \rightarrow \mathbb{R}$$

$$\text{gegeven door } \langle \underline{u}, \underline{v} \rangle = \int_{-1}^1 \underline{u}(x) \underline{v}(x) dx.$$

$$a. \langle \underline{u}, \underline{v} \rangle = \int_{-1}^1 \underline{u}(x) \underline{v}(x) dx = \langle \underline{v}, \underline{u} \rangle.$$

1

$$\langle c \underline{u}, \underline{v} \rangle = \int_{-1}^1 c \underline{u} \underline{v} dx = c \int_{-1}^1 \underline{u} \underline{v} dx = c \langle \underline{u}, \underline{v} \rangle$$

$c \in \mathbb{R}$

1

$$\langle \underline{u} + \underline{v}, \underline{w} \rangle = \int_{-1}^1 (\underline{u} + \underline{v}) \underline{w} \, dx = \int_{-1}^1 \underline{u} \underline{w} \, dx + \int_{-1}^1 \underline{v} \underline{w} \, dx$$

$$= \langle \underline{u}, \underline{w} \rangle + \langle \underline{v}, \underline{w} \rangle.$$

$$\langle \underline{u}, \underline{u} \rangle = \int_{-1}^1 \underline{u}^2 \, dx \geq 0 \quad \text{and}$$

$$\text{since } u^2(x) \geq 0 \, \forall x, \quad \int_{-1}^1 u^2(x) \, dx = 0 \Leftrightarrow u^2(x) = 0 \, \forall x.$$

(an u is zero)

$$b. \quad \langle 1, 2x-1 \rangle = \int_{-1}^1 2x-1 \, dx = \left[x^2 - x \right]_{-1}^1 = 0.$$

$$\langle 1, x^2 - x + \frac{1}{6} \rangle = \int_{-1}^1 x^2 - x + \frac{1}{6} \, dx = \left[\frac{1}{3}x^3 - \frac{1}{2}x^2 + \frac{1}{6}x \right]_{-1}^1 = 0$$

$$\langle 2x-1, x^2 - x + \frac{1}{6} \rangle = \int_{-1}^1 (2x-1)(x^2 - x + \frac{1}{6}) \, dx$$

$$= \dots = 0.$$

$$c. \quad T(\underline{p}) = x \underline{p}'(x).$$

$$B = \{ \underline{b}_1, \underline{b}_2, \underline{b}_3 \}$$

$$= \{ 1, 2x-1, x^2 - x + \frac{1}{6} \}.$$

$$T(\underline{b}_1) = 0.$$

$$T(\underline{b}_2) = 2x = \underline{b}_1 + \underline{b}_2$$

$$T(\underline{b}_3) = x(2x-1) = 2x^2 - x = 2\underline{b}_3 + \frac{1}{2}\underline{b}_2 + \frac{1}{6}\underline{b}_1$$

$$D_m [T]_B = \begin{bmatrix} 0 & 1 & \frac{1}{6} \\ 0 & 1 & \frac{1}{2} \\ 0 & 0 & 2 \end{bmatrix}$$