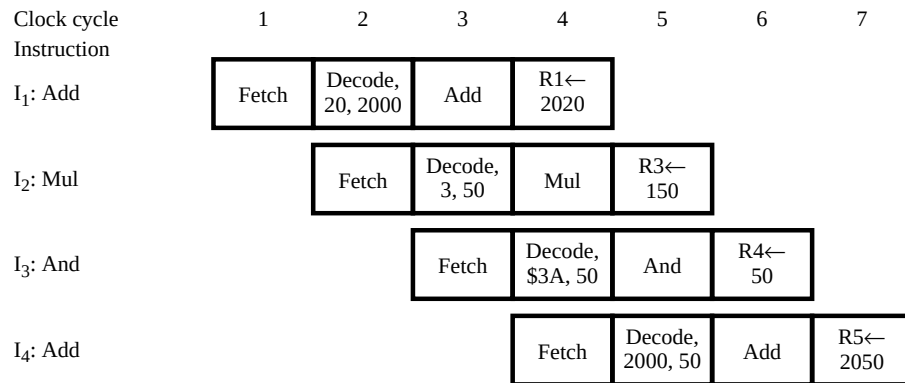


Chapter 8 – Pipelining

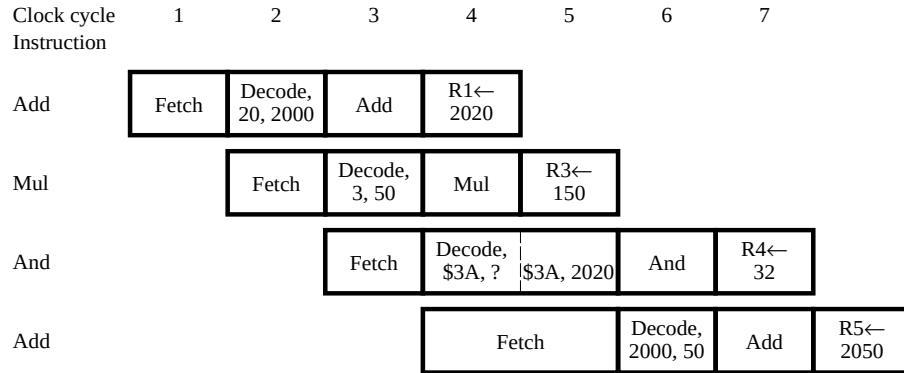
8.1. (a) The operation performed in each step and the operands involved are as given in the figure below.



(b)

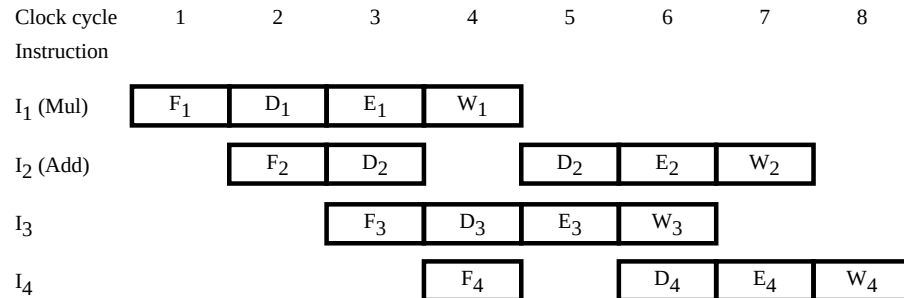
Clock cycle	2	3	4	5
Buffer B1	Add instruction (I ₁)	Mul instruction (I ₂)	And instruction (I ₃)	Add instruction (I ₄)
Buffer B2	Information from a previous instruction	Decoded I ₁ Source operands: 20, 2000	Decoded I ₂ Source operands: 3, 50	Decoded I ₃ Source operands: \$3A, 50
Buffer B3	Information from a previous instruction	Information from a previous instruction	Result of I ₁ : 2020 Destination = R1	Result of I ₂ : 150 Destination = R3

8.2. (a)

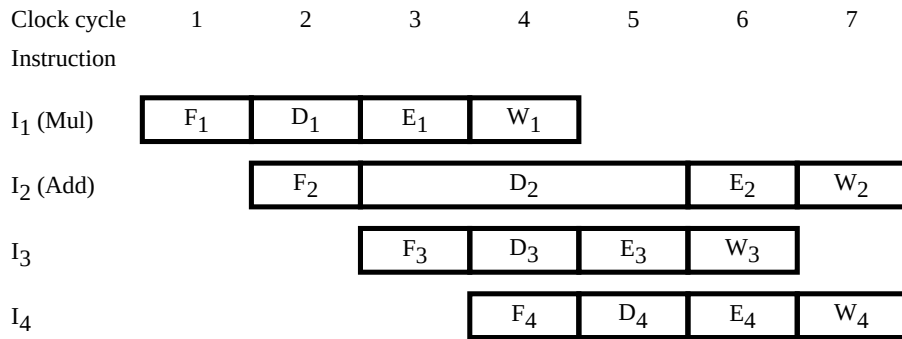


(b) Cycles 2 to 4 are the same as in P8.1, but contents of R1 are not available until cycle 5. In cycle 5, B1 and B2 have the same contents as in cycle 4. B3 contains the result of the multiply instruction.

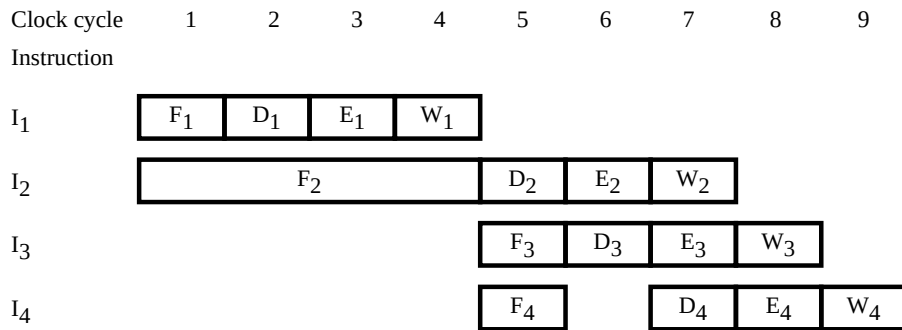
8.3. Step D₂ may be abandoned, to be repeated in cycle 5, as shown below. But, instruction I₁ must remain in buffer B1. For I₃ to proceed, buffer B1 must be capable of holding two instructions. The decode step for I₄ has to be delayed as shown, assuming that only one instruction can be decoded at a time.



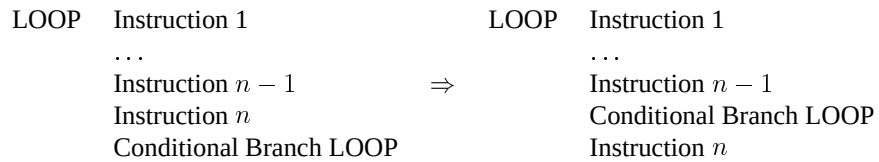
8.4. If all decode and execute stages can handle two instructions at a time, only instruction I_2 is delayed, as shown below. In this case, all buffers must be capable of holding information for two instructions. Note that completing instruction I_3 before I_2 could cause problems. See Section 8.6.1.



8.5. Execution proceeds as follows.



8.6. The instruction immediately preceding the branch should be placed after the branch.



This reorganization is possible only if the branch instruction does not depend on instruction n .

- 8.7. The UltraSPARC arrangement is advantageous when the branch instruction is at the end of the loop and it is possible to move one instruction from the body of the loop into the delay slot. The alternative arrangement is advantageous when the branch instruction is at the beginning of the loop.
- 8.8. The instruction executed on a speculative basis should be one that is likely to be the correct choice most often. Thus, the conditional branch should be placed at the end of the loop, with an instruction from the body of the loop moved to the delay slot if possible. Alternatively, a copy of the first instruction in the loop body can be placed in the delay slot and the branch address changed to that of the second instruction in the loop.
- 8.9. The first branch (BLE) has to be followed by a NOP instruction in the delay slot, because none of the instructions around it can be moved. The inner and outer loop controls can be adjusted as shown below. The first instruction in the outer loop is duplicated in the delay slot following BLE. It will be executed one more time than in the original program, changing the value left in R3. However, this should cause no difficulty provided the contents of R3 are not needed once the sort is completed. The modified program is as follows:

	ADD	R0,LIST,R3	
	ADD	R0,N,R1	
	SUB	R1,1,R1	
	SUB	R1,1,R2	
OUTER	LDUB	[R3+R1],R5	Get LIST(j)
	LDUB	[R3+R2],R6	Get LIST(k)
INNER	SUB	R6,R5,R0	
	BLE,pt	NEXT	
	SUB	R2,1,R2	$k \leftarrow k-1$
	STUB	R5,[R3+R2]	
	STUB	R6,[R3+R1]	
	OR	R0,R6,R5	
NEXT	BGE,pt,a	INNER	
	LDUB	[R3+R2],R6	Get LIST(k)
	SUB	R1,1,R1	
	BGT,pt	OUTER	
	SUB	R1,1,R2	

8.10. Without conditional instructions:

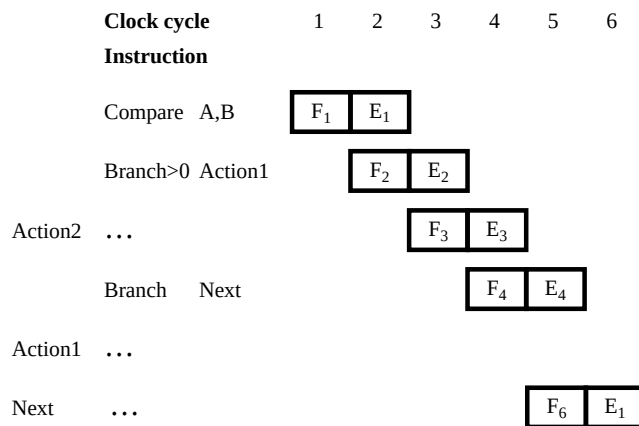
	Compare	A,B	Check A – B
	Branch>0	Action1	
Action2	...	...	One or more instructions
	Branch	Next	
Action1	...	...	One or more instructions
Next	...		

If conditional instructions are available, we can use:

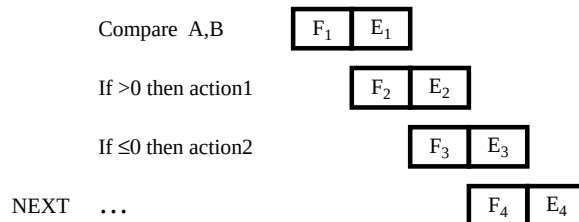
	Compare	A,B	Check A – B
	...	...	Action1 instruction(s), conditional
	...	...	Action2 instruction(s), conditional
Next	...		

In the second case, all Action 1 and Action 2 instructions must be fetched and decoded to determine whether they are to be executed. Hence, this approach is beneficial only if each action consists of one or two instructions.

Without conditional instructions



With conditional instructions



8.11. Buffer contents will be as shown below.

Clock				
Cycle No.	3	4	5	
ALU Operation	+	Shift	O ₃	
R3	45	130	260	
RSLT	198	130	260	

8.12. Using Load and Store instructions, the program may be revised as follows:

INSERTION	Test	RHEAD
	Branch>0	HEAD
	Move	RNEWREC,RHEAD
	Return	
HEAD	Load	RTEMP1,(RHEAD)
	Load	RTEMP2,(RNEWREC)
	Compare	RTEMP1,RTEMP2
	Branch>0	SEARCH
	Store	RHEAD,4(RNEWREC)
	Move	RNEWREC,RHEAD
	Return	
SEARCH	Move	RHEAD,RCURRENT
LOOP	Load	RNEXT,4(RCURRENT)
	Test	RNEXT
	Branch=0	TAIL
	Load	RTEMP1,(RNEXT)
	Load	RTEMP2,(RNEWREC)
	Compare	RTEMP1,RTEMP2
	Branch<0	INSERT
	Move	RNEXT,RCURRENT
	Branch	LOOP
INSERT	Store	RNEXT,4(RNEWREC)
TAIL	Store	RNEWREC,4(RCURRENT)
	Return	

This program contains many dependencies and branch instructions. There very few possibilities for instruction reordering. The critical part where optimization should be attempted is the loop. Given that no information is available on branch behavior or delay slots, the only optimization possible is to separate instructions that depend on each. This would reduce the probability of stalling the pipeline.

The loop may be reorganized as follows.

LOOP	Load	RNEXT,4(RCURRENT)
	Load	RTEMP2,(RNEWREC)
	Test	RNEXT
	Load	RTEMP1,(RNEXT)
	Branch=0	TAIL
	Compare	RTEMP1,RTEMP2
	Branch<0	INSERT
	Move	RNEXT,RCURRENT
	Branch	LOOP
INSERT	Store	RNEXT,4(RNEWREC)
TAIL	Store	RNEWREC,4(RCURRENT)
	Return	

Note that we have assumed that the Load instruction does not affect the condition code flags.

- 8.13. Because of branch instructions, 120 clock cycles are needed to execute 100 program instructions when delay slots are not used. Using the delay slots will eliminate 0.85 of the idle cycles. Thus, the improvement is given by:

$$\frac{120}{120 - 20 \times 0.85} = 1.081$$

That is, instruction throughput will increase by 8.1%.

- 8.14. Number of cycles needed to execute 100 instructions:

Without optimization	140
With optimization ($140 - 20 \times 0.85 - 20 \times 0.2$)	127

Thus, throughput improvement is $140/127 = 1.102$, or 10.2%

- 8.15. Throughput improvement due to pipelining is n , where n is the number of pipeline stages.

	Number of cycles needed to execute one instruction:	Throughput
4-stage:	$1.20 - 0.8 \times 0.20 = 1.04$	$4/1.04 = 3.85$
6-stage:	$1.4 - 0.8 \times 0.2 - 0.25 \times 0.2 = 1.19$	$6/1.19 = 5.04$

Thus, the 6-stage pipeline leads to higher performance.

8.16. For a “do while” loop, the termination condition is tested at the beginning of the loop. A conditional branch at that location will be taken when exiting the loop. Hence, it should be predicted not taken. That is, the state machine should be started in the state LNT, unless the loop is not likely to be executed at all.

A “do until” loop is executed at least once, and the branch condition is tested at the end of the loop. Assuming that the loop is likely to be executed several times, the branch should be predicted taken. That is, the state machine should be started in state LT.

8.17. An instruction fetched in cycle j reaches the head of the queue and enters the decode stage in cycle $j + 6$. Assume that the instruction preceding I_1 is decoded and instruction I_6 is fetched in cycle 1. This leads to instructions I_1 to I_6 being in the queue at the beginning of cycle 2. Execution would then proceed as shown below.

Note that the queue is always full, because at most one instruction is dispatched and up to two instructions are fetched in any given cycle. Under these conditions, the queue length would drop below 6 only in the case of a cache miss.

